## **Dual PID Control Temperature Controller**

### Features

Dual PID auto tuning function:
 High-speed response of PID control to reach to the
 desired value fast, low-speed of response of PID control
 to minimize the overshoot even though response is a
 little bit slow.

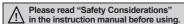
- High display accuracy: ±0.3% (by F.S. value of each input)
- 2-step auto tuning control function
- Multi-input function

(13 kinds of multi-input selection function): Temperature sensor, voltage and current selection function.

 Various sub output function: Includes in LBA, SBA, 7 kinds of alarm output and 4 kinds of alarm option function, PV transmission output (DC4-20mA), RS485 communication output

Display the decimal point for analog input



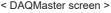




### Comprehensive Device Management Program (DAQMaster)

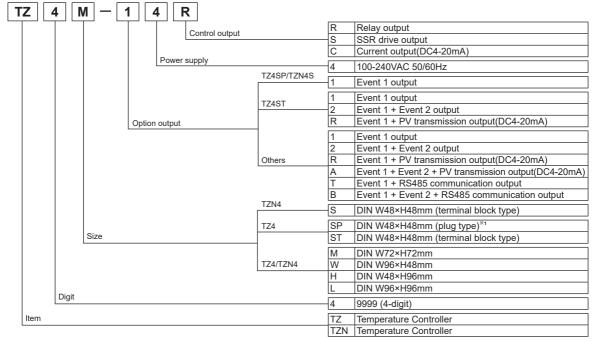
- DAQMaster is comprehensive device management program for convenient management of parameters and multiple device data monitoring.
- Visit our website (www.autonics.com) to download user manual and comprehensive device management program.
- < Computer specification for using software >

Item	Minimum requirements
System	IBM PC compatible computer with Intel Pentium III or above
Operating system	Microsoft Windows 98/NT/XP/Vista/7/8/10
Memory	256MB or more
Hard disk	More than 1GB of free hard disk space
VGA	1024×768 or higher resolution display
Others	RS-232 serial port (9-pin), USB port





# Ordering Information



※The unit cannot be configured with any random combination from the above ordering information. Please refer to '■ Specifications' for possible configurations.

X1: 11-pin sockets (PG-11, PS-11(N)) are sold separately.

J-140 Autonics

# Specifications

Series		TZ4SP TZN4S	TZ4ST	TZ4M TZN4M	TZ4W TZN4W	TZ4H TZN4H	TZ4L TZN4L	SEN
Power su	ipply	100-240VAC~ 50	/60Hz					
Allowable	voltage range	90 to 110% of rate	d power voltage					co
Power co	nsumption	Max. 5VA (100-24	0VAC∼ 50/60Hz)	Max. 6VA (100-2	40VAC∼ 50/60Hz)	ı		
Display m	nethod	7-segment LED (F	V: red, SV: green)					
Character size (W×H)	PV	TZ4SP: 4.8×7.8mm TZN4S: 7.8×11.0mm	4.047.0	TZ4M: 9.8×14.2mm TZN4M: 8.0×13.0mm	0.0040.00	<b>TZ4H:</b> 3.8×7.6mm <b>TZN4H:</b> 7.8×11.0mm	9.8×14.2mm	SOI
Charact (Wx	SV	TZ4SP: 4.8×7.8mm TZN4S: 5.8×8.0mm	-4.8×7.8mm	TZ4M: 8.0×10.0mm TZN4M: 5.0×9.0mm		<b>TZ4H:</b> 3.8×7.6mm <b>TZN4H:</b> 5.8×8.0mm	8.0×10.0mm	
	RTD	DPt100Ω, JPt100	Ω, 3-wire (allowed	resistance: max. 5	Ω per line)	'		
Input	TC	K(CA), J(IC), R(PI	R), E(CR), T(CC), S	S(PR), N(NN), W(T	T) (allowed resista	ince: max. 100Ω pe	er line)	
type	Analog	1-5VDC==, 0-10VI	DC==, DC4-20mA				,	
Display a		F.S. ±0.3% or 3°C	greater value					(J) Ter
<del></del> .	Relay	250VAC~ 3A, 30	-					Co
Control	SSR	Max. 12VDC== ±3						
output	Current		esistance max. 60	0Ω)				(K) SS
	EVENT1	250VAC~ 1A 1a		011)				
	EVENT2		250VAC∼ 1A 1a					(L)
- P	PV transmission			resistance may 60	100)			Po
Output     PV transmission     —     DC4-20mA (load resistance max. 600Ω)       Communication     —     RS485 communication								
Control m		ON/OFE P PL PE	DIDE DIDS contr		oation			(M)
Control method ON/OFF, P, PI, PD, PIDF, PIDS control  Alarm output hysteresis 1 to 100°C (0.1 to 100.0°C) variable						Co		
Proportional band (P) 0.0 to 100.0%								
Integral time (I)		+	0 to 3,600 sec					
Derivative time (D)		0 to 3,600 sec						
Control pe		1 to 120 sec						(O)
<u>.</u>		0.5 sec						Dig Pa
Sampling		1 to 999 sec	-					-
LBA settir			2					(P)
Ramp set		Ramp Up, Ramp Down: 1 to 99 min each 2,000VAC 50/60Hz for 1 min (between input and power terminals)					Ind	
Dielectric						ation for 0 barre		
Vibration	Mechanical	· · · · ·			in each X, Y, Z dire			(Q) Co
	Electrical	<del>'</del>			each X, Y, Z direc	tion for 10 min		
Dalari	Control output		10,000,000 operati	,	nco load)			(R)
Relay life cycle		Electrical: min. 100,000 operations (250VAC 3A resistance load)  Mechanical: min. 20,000,000 operations.						Dig
ine cycle	Option output		20,000,000 operati 0,000 operations (2	,	nce load)			
Insulation	ı resistance	Over 100MΩ (at 5	· · · · · · · · · · · · · · · · · · ·		,			(S) Se
Noise imr		,	- 00 /	ator (pulse width 1	us) +2kV R-nhase	S-phase		Co
Noise immunity  Square shaped noise by noise simulator (pulse width 1µs) ±2kV R-phase, S-phase Memory retention  Approx. 10 years (non-volatile semiconductor memory type)		- p		(T)				
		-10 to 50°C, storage: -20 to 60°C						(T) Sw Mo
ment		35 to 85%RH, sto		<u> </u>				Su
	Transient nuitii.		age. 55 to 65 /6KF	•				
Approval		<b>€ c<b>FL</b>°us</b>	ı	I==		I==		(U) Re
Weight <sup>×1</sup>		TZ4SP: approx. 205g (approx. 144g) TZN4S:	Approx. 218g (approx. 162g)	approx. 360g (approx. 228g)	<b>TZ4W:</b> approx. 365g (approx. 246g) <b>TZN4W:</b>	<b>TZ4H:</b> approx. 365g (approx. 246g) <b>TZN4H:</b>	TZ4L: approx. 474g (approx. 304g) TZN4L:	(V) HM
	weight includes n	approx. 226g (approx. 164g)	aht in paranthasis i	approx.355g (approx. 246g)	approx. 351g (approx. 232g)	approx. 351g (approx. 232g)	approx. 474g (approx. 303g)	(W

 $<sup>\</sup>times$  1: The weight includes packaging. The weight in parenthesis is for unit only.  $\times$  Environment resistance is rated at no freezing or condensation.

SENSORS CONTROLLERS

MOTION DEVICES

(X) Field Network Devices

J-141 **Autonics** 

# **TZN/TZ Series**

### Connections

 $\times$ RTD: DPt100Ω (3-wire type), JPt100Ω (3-wire type)

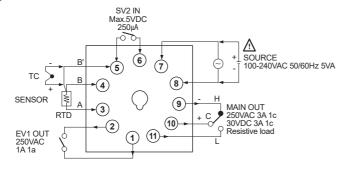
XTC (Thermocouple): K(CA), J(IC), R(PR), E(CR), T(CC), S(PR), N(NN), W(TT)

XIn case of analog input, please use TC (Thermocouple) terminal and be careful about polarity.

XUse teminals of size specified below.

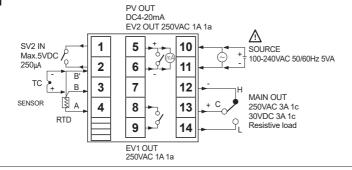
	Round>	Forked>
а	Min. 3.5mm	Min. 3.5mm
b	Max. 7.2mm	Max. 7.2mm

#### TZ4SP



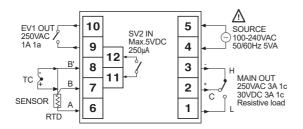
MAIN OUT				
SSR	Current			
9 · V	9 - mA			
12VDC ±3V 30mA Max.	DC4-20mA Load 600Ω Max.			

#### TZ4ST



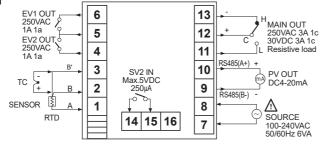
MAIN OUT				
SSR	Current			
12	12 mA			
12VDC ±3V 30mA Max.	DC4-20mA Load 600Ω Max.			

#### TZN4S



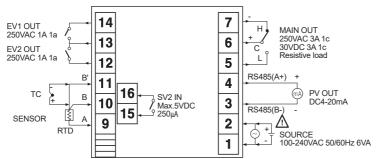
MAIN OUT				
SSR Current				
3 ()	3 2 +			
12VDC ±3V 30mA Max.	DC4-20mA Load 600Ω Max.			

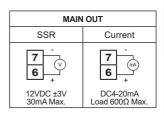
#### TZ4M



MAIN OUT				
SSR	Current			
13 12 12VDC ±3V 30mA Max.	13 12 + DC4-20mA Load 600Ω Max.			







SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

#### TZ4W/TZN4W

TZ4H/TZN4H

EV1 OUT 250VAC 1A 1a

EV2 OUT 250VAC 1A 1a

> SV2 IN Max.5VDC A 250µA

> > TC

SENSOR

8

7

6

5

4

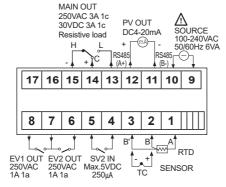
3

2

1

В

RTD



17

16

15

14

13

12

11

10

9

H MAIN OUT 250VAC 3A 1c 30VDC 3A 1c L Resistive load

PV OUT DC4-20mA

SOURCE

100-240VAC 50/60Hz 6VA

С

RS485(B-) -

MAIN	MAIN OUT				
SSR	SSR Current				
15	15 mA				
12VDC ±3V 30mA Max.	DC4-20mA Load 600Ω Max.				

MAIN OUT

Current

(mA)

15

14

DC4-20m4

SSR

Ŷ

15

14

12\/DC +3\/

30mA Max.

#### (J) Temperature Controllers

(K) SSRs

Power Controllers (M) Counters

)

(N) Timers

(O) Digital Panel Meters

(P) Indicators

(Q) Converters

(R) Digital Display Units

(S) Sensor Controllers

(T) Switching Mode Power Supplies

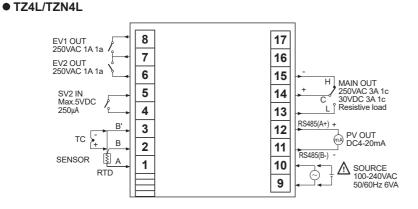
(U) Recorders

.

(V) HMIs

(W) Panel PC (X) Field Network

Devices

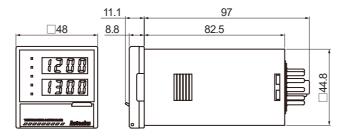


MAIN OUT		
SSR	Current	
15 14	15 mA	
12VDC ±3V 30mA Max.	DC4-20mA Load 600Ω Max.	

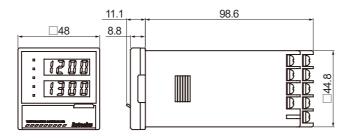
### Dimensions

• TZ4SP

(unit: mm)

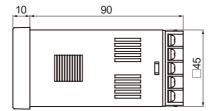


#### • TZ4ST

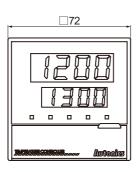


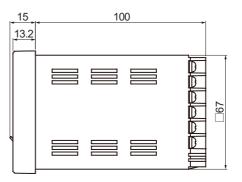
#### TZN4S



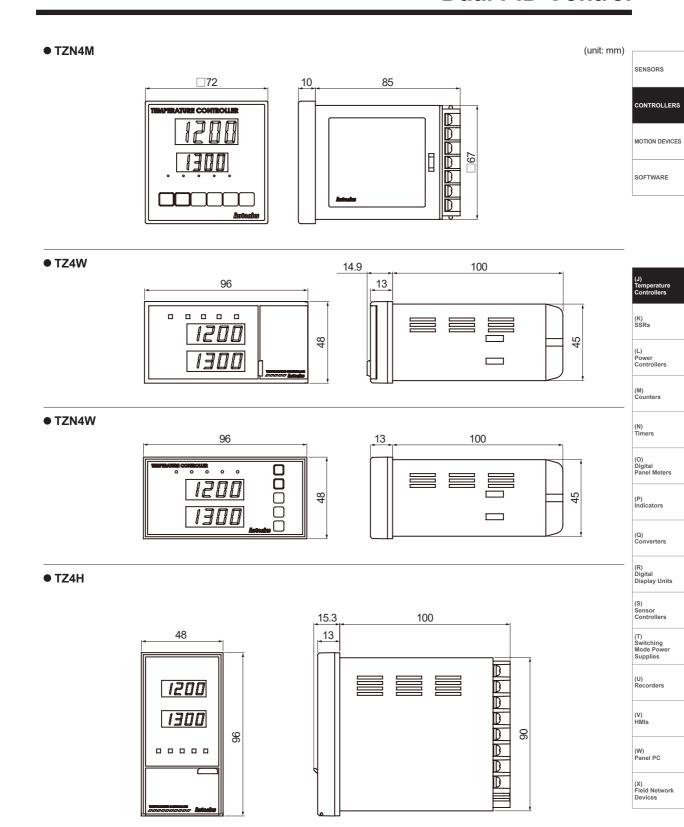


### • TZ4M

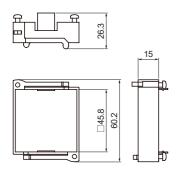




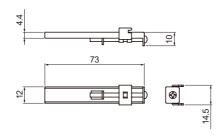
J-144 Autonics



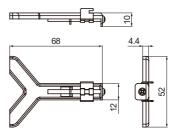
- Bracket
- TZ4ST, TZ4SP, TZN4S Series



• TZ4L, TZN4L, TZ4M, TZ4H, TZN4H, TZN4H, TZN4W Series



TZN4M Series



SENSORS

(unit: mm)

CONTROLLERS

MOTION DEVICES

SOFTWARE

### Sold Separately

- **©** Communication converter



• SCM-US48I (USB to RS485 converter)

**C**€ 🖫



• SCM-38I (RS232C to RS485 converter)

**(€** 🖫



# **■** Input Type and Range

Input type		Decimal point	Display	Temperature range (°C) Temperature range (°F)	
	K(CA)	1	L C U'H	-100 to 1300	-148 to 2372
	K(CA)	0.1	L C U L	-100.0 to 999.9	Not supported
	J(IC)	1	JI C.H	0 to 800	32 to 1472
	J(IC)	0.1	JI C.L	0.0 to 800.0	Not supported
	R(PR)	1	r Pr	0 to 1700	32 to 3092
Thermoneounle	E(CR)	1	E C r.H	0 to 800	32 to 1472
Thermocouple	E(CR)	0.1	E C r.L	0.0 to 800.0	Not supported
	T(CC)	1	E € €.H	-200 to 400	-328 to 752
	T(CC)	0.1	E C C.L	-199.9 to 400.0	Not supported
	S(PR)	1	5 Pr	0 to 1700	32 to 3092
	N(NN)	1	Ппп	0 to 1300	32 to 2372
	W(TT)	1	UEE	0 to 2300	32 to 4172
	JPt100Ω	1	JPE.H	0 to 500	32 to 932
DTD	JPt100Ω	0.1	JP E.L	-199.9 to 199.9	-199.9 to 391.8
RTD	DPt100Ω	1	dPt.H	0 to 500	32 to 932
	DPt100Ω	0.1	dPt.L	-199.9 to 199.9	-199.9 to 391.8
		0 - 10VDC	R1		
Analog	Voltage	1 - 5VDC	R2	-1999 to 9999  (display range will vary depending on the decimal point.)	
	Current	DC4 - 20mA	R3		

Temperature Controllers

K) SSRs

(L) Power Controllers

(M) Counters

(N) Timers

(O) Digital Panel Meters

(P) Indicators

(Q) Converters

(R) Digital Display Units

(S) Sensor Controllers

(T) Switching Mode Power Supplies

(U) Recorders

(V) HMIs

(W) Panel PC

(X) Field Network Devices

### Configuring Input Type

Please configure the internal switches before supplying power. After supplying power, configure the input type [! n-t] in parameter group 2 according to the input type.

Input type		S/W 1	S/W 2
Thermocouple			1董
RTD		1 1	mA V
Analog	Voltage (0-10VDC, 1-5VDC)	2 2	mA V
	Current (DC4-20mA)	2 2	mA V

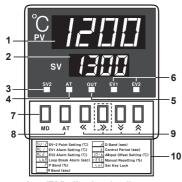
#### • Detaching the case

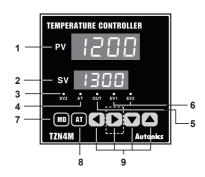


Press the front case then pull the case to detach the case from the body.

Configure the internal switches as input type.

### Unit Description





1. Present value (PV) display (red):

RUN mode: displays the current value (PV)

Setting mode: displays parameters

2. Set value (SV) display (green):

RUN mode: displays the set value (SV)

Setting mode: displays parameter setting values

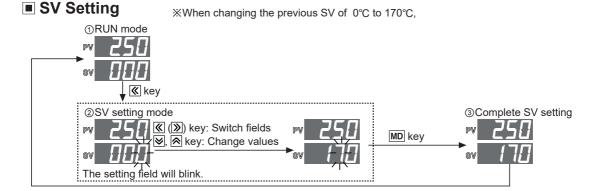
- 3. SV2 operation indicator: turns ON when SV2 is operating
- 4. Auto-tuning indicator: turns ON when auto-tuning
- **5. Control output operation indicator**: turns ON when control output is ON. Does not operate when the control output is current output.
- 6. Event output indicator: turns ON when the according event output is ON.

\*The Event 2 output indicator does not operate in TZ4SP.

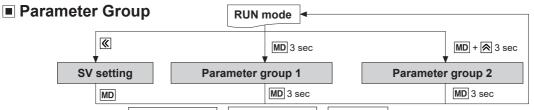
- 7. Mode key: enter parameter group, return to RUN mode, switch parameters, save setting values
- 8. Auto-tuning key: hold the key for 3 sec to start auto-tuning. Hold the key for 5 sec while auto-tuning to stop auto-tuning.
- **9. Setting keys**: enter SV change mode, switch fields, change value

() key in the dotted line is only available in TZ4M and TZ4L models)

#### 10. Key adjustment order chart



J-148 Autonics



※Parameter setting order Parameter group 2 → Parameter group 1 → SV setting

Lock

LoC

The parameters are related to each other. Please set the parameters in the order above.

\*When there is no key input for 60 sec while in SV setting mode or parameter groups, the unit will return to RUN mode automatically.

 Parameter group 1 X2: Press the MD key after checking or changing the values in parameter settings to MD 3 sec save the setting value and move to the next parameter. ►RUN mode value and return to RLIN mode MD 3 sec \*The dotted line parameters : may not appear depending on the model or other parameter settings. PV display SV display S ×1 Setting range: refer to '■ Input Type and Range'. 50-2 0 temperature MD ×2 Event 1 Setting range: refer to ' Input Type and Range'. S AL 10 alarm ※[AL 1, AL 2] parameters do not appear when Event 1/2 [EU-1, EU-2] of parameter temperature (L) group 2 is set to AL - D, LbA, 5bA. Power Controllers ※[AL2] parameter only appears in models that support Event 2 output. Event 2 S RL2 10 alarm temperature (M) Counters Setting range: 0 to 999 sec LBA ※Only appears when Event1/2 [EU-1, EU-2] of parameter group 2 is set to LbA. LЬЯ 600 monitoring XDoes not appear in current output models. time (N) Timers Alarm Setting range: 1 to 100°C/°F (0.1 to 100.0°C/°F) S 2 RH45 output ※Does not appear when Event 1/2 [EU-1, EU-2] of parameter (O) Digital Panel Meters hysteresis group 2 is set to AL - D, LbA, 5bA. S Setting range: 0.0 to 100.0% Proportional P 3.0 band ※ON/OFF control: Set to □□. PID control: Set to over □□ (P) Indicators S Integral Setting range: 0 to 3,600 sec 0 (Q) Converters XIntegral operation is turned OFF when set to □. XOnly appears during PID S Derivative Setting range: 0 to 3,600 sec 0 (R) Digital Ь control (proportional band time ※Derivative operation is turned OFF when set to □. Display Units [P] set to over [].[]). (S) S Control Setting range: 1 to 120 sec Sensor Controllers 20 Ŀ XSet to a small value in SSR drive output models. (e.g. 2 sec) period XDoes not appear in current output models. (T) Switching Mode Powe S Setting range: 1 to 100°C/°F (0.1 to 100.0°C/°F) 2 H45 Hysteresis Supplies ※Only appears during ON/OFF control (proportional band [P] set to □□). (U) Recorders S Input 10-6 0 Setting range: -49 to 50°C/°F (-50.0 to 50.0°C/°F) correction Setting range: 0.0 to 100% (V) HMIs S Manual rE5E 0.0 ※Only appears when P control (proportional band [P] set to over □□, integral time [I]. reset and derivative time [d] are set to []) (W) Panel PC Ramp S - RPU 10 Setting range: 1 to 99 min up time ※Only appears when ramp function [¬ Ħ n̄ P] of parameter group (X) Field Network 2 is set to on. S Ramp 10 rRPd down time Setting range: □FF Unlock Lock parameter 1 (AT key available)

CONTROLLERS

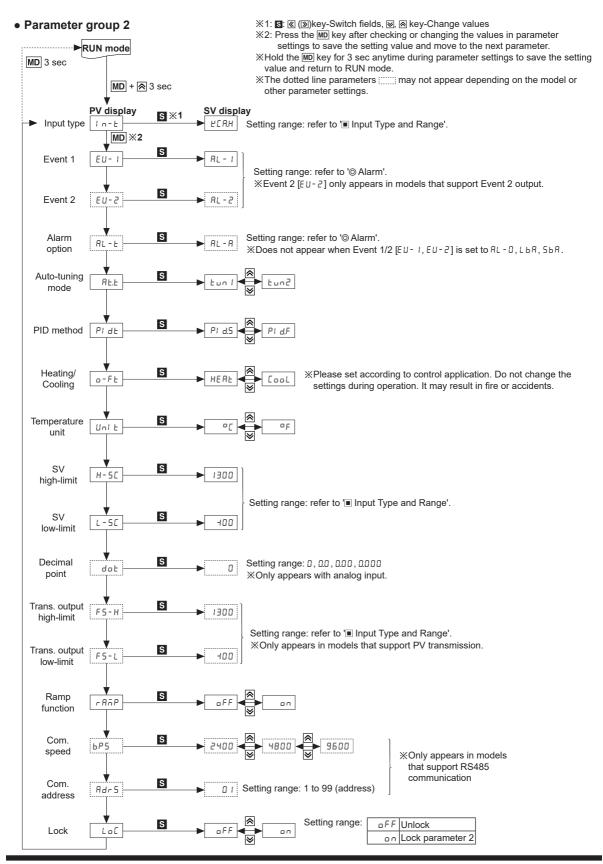
SENSORS

MOTION DEVICES

SOFTWARE

.I<sub>-</sub>149 Autonics

Lock parameter 1 (AT key unavailable)



### Factory Defaults

#### Parameter group 1

Parameter	Default	Parameter	Default	Parameter	Default
50-2	0	Р	3.0	In-b	0
AL I	10	1	0	rESt	0.0
AL 2	10	Ь	0	r A P U	10
LЬЯ	600	Ŀ	20	rAPd	10
AHY5	2	H95	2	LoC	oFF

#### • Parameter group 2

Parameter	Default	Parameter	Default	Parameter	Default
In-E	E C B.H	o-Ft	HERL	F5-L	400
EU-I	AL-I	Uni E	٥٢	rAñP	oFF
EU-2	AL-2	H-5[	1300	6P5	2400
AL-E	AL-A	L-5E	400	Adr5	01
A Ł.Ł	tun I	dot	0	LoC	oFF
PI dE	P1 d.5	F5-H	1300		

#### SENSORS

CONTROLLERS

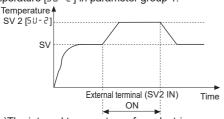
MOTION DEVICES

SOFTWARE

#### Functions

### O SV 2 temperature

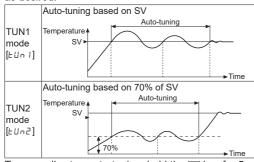
You can control an additional temperature value at a desired range by using SV2. Connect a contact signal (under 5VDC,  $250\mu$ A) at the external terminal, to operate in the range where the signal turns ON. Set the SV2 temperature in SV2 temperature [5U-2] in parameter group 1.



E.g.)The internal temperature of an electric oven may drop rapidly if the door is opened while the oven is maintaining a specific temperature. Set SV2 temperature [5U-2] to a higher value than SV, and input a signal to the external terminal (SV2 IN), to quickly raise the temperature.

### Auto-tuning

Auto-tuning allows the temperature controller to detect the thermal characteristics and response rates of the control target. It then calculates the PID time constant and sets the value to allow fast response rates and high accuracy. Hold the lateral temperature in the auto-tuning RUN mode to start auto-tuning. The auto-tuning indicator will blink. When auto-tuning is completed, the auto-tuning indicator will durn off and the PID time constant will be saved to each parameter of parameter group 1. The saved parameters can be adjusted as desired.



To manually stop auto-tuning, hold the  $\boxed{\mathtt{AT}}$  key for 5 sec. When auto-tuning is stopped, the controller maintains the PID value before auto-tuning. TZ Series supports 2 auto-tuning modes.

Select TUN1 mode or TUN2 mode [£Un I, £Un 2] from auto-tuning mode [A££] of parameter group 2.

※Run auto-tuning during initial setup of the temperature controller.

※If the thermal characteristics of the control target device has changed after extended usage, re-run auto-tuning.

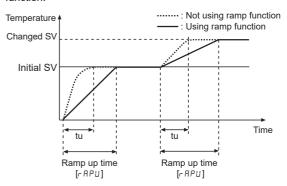
#### Ramp

The ramp function can delay the rate of temperature rise/fall. If the SV value is changed during stabilized control, the temperature of the controlled target will rise/fall during ramp up/down time [¬ЯРШ,¬ЯРЫ] of parameter group 1. The ramp function activates when the power is reset or when the SV value is changed during stable control.

\*\*The ramp up/down time [- #PU, - #PU] appear only when the ramp function [- #nP] of parameter group 2 is set to an.

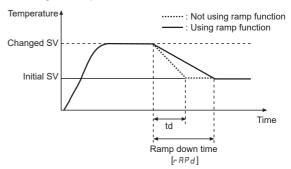
#### ●RAMP up time[r用PU]

When delaying the rise of initial control temperature or changing the SV during stable control, you can delay temperature rise. Set the ramp up time [- RPU] longer than the temperature rise time (tu) when not using the ramp function.



#### ●Ramp down time [r用Pd]

Delays declining temperature. Set the ramp down time [- RPd] longer than the temperature decline time (td) when not using the ramp function.



J) Temperature Controllers

i) SRs

(L) Power Controllers

(M) Counters

(N) Timers

(O) Digital Panel Meters

(P) Indicators

(Q) Converters (R) Digital

Display Units

(S)
Sensor
Controllers

(T) Switching Mode Power Supplies

(U) Recorders

(V) HMIs

(W) Panel PC

(X) Field Network Devices

# **TZN/TZ Series**

#### Alarm (event)

Alarm output can be configured by combining alarm operation and alarm options. Set the alarm operation in event 1/2 [E U I, E U d] of parameter group 2, and set the alarm options in alarm option [AL - E].

#### 1) Alarm operation

Mode	Name	Alarm operation		Description
AL - 0	I—	_		Alarm output not used.
AL-I	Deviation high-limit alarm	SV	H ↑ ON △ PV 110°C ation: 10°C	If the deviation of PV and SV are higher than the high-limit deviation, the alarm output turns ON.
AL-2	Deviation low-limit alarm	ON H PV 90°C Low-limit devia	OFF SV 100°C ation: 10°C	If the deviation of PV and SV are higher than the low-limit deviation, the alarm output turns ON.
AL-3	Deviation high-limit /low-limit alarm	ON H OFF  ON SV 90°C 100°C  High-limit/low-limit		If the deviation of PV and SV are higher than the high-limit deviation or low-limit deviation, the alarm output turns ON.
AL-4	Deviation high-limit /low-limit reverse alarm	OFF H ON  PV SV 90°C 100°C  High-limit/low-limit		If the deviation of PV and SV are higher than the high-limit deviation or low-limit deviation, the alarm output turns OFF.
AL-5	Absolute value high-limit alarm	OFF H ON  A  PV SV  90°C 100°C  Absolute value alarm: 90°C	OFF H ON  SV PV  100°C 110°C  Absolute value alarm: 110°C	Alarm output turns ON when PV is higher than the absolute value.
AL-6	Absolute value low-limit alarm	ON H OFF  A PV SV 90°C 100°C  Absolute value alarm: 90°C	ON H OFF  SV PV  100°C 110°C  Absolute value alarm: 110°C	Alarm output turns ON when PV is lower than the absolute value.
56A	Sensor break	_		Alarm output turns ON when sensor disconnection is detected.
LbA	Loop break	_		Alarm output turns ON when loop break is detected.

#### ※ H: Alarm output hysteresis[AHY5]

#### 2) Alarm options

Mode	Name	Description
AL-A	Standard alarm	Alarm output turns ON upon alarm condition, and alarm output turns OFF when condition is cleared.
AL-P	Alarm latch	Alarm output turns ON and maintains ON upon alarm condition.
AL-C	Standby sequence	The first alarm condition is ignored. It will operate as standard alarm from the second alarm condition. If it is under alarm condition when power is supplied, it will ignore the condition and operate as standard alarm from the next alarm condition.
AL-d	Alarm latch and standby sequence	It will operate as both alarm latch and standby sequence upon alarm condition. If it is under alarm condition when power is supplied, it will ignore the condition and operate as alarm latch from the next alarm condition.

#### 3) Sensor break alarm

Alarm output turns ON when sensor is not connected or loses its connection during temperature control. Sensor disconnection can be tested by connecting buzzers or other devices to the alarm output contact. Sensor break alarm output operates through EV1 OUT or EV2 OUT contacts. Alarm output is disengaged after resetting the power.

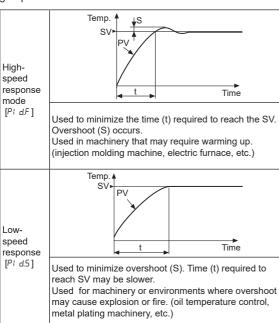
#### 4) Loop break Alarm (LBA)

Diagnose control loop and transmit alarm output through temperature change of control target. During heating(cooling) control, the alarm output turns ON if the PV does not rise/drop by a specific amount (approx. 2°C) during LBA monitoring period [L b A] while control output amount is at 100%(0%).

- ※If the thermal response of the control target is slow, the LBA monitoring period [L b R] of parameter group 1 should be set longer.
- \*\*LBA only operates when the control output amount is 100%(0%) so it cannot be used in current output models.
- XIf the alarm output turns ON after the sensor has been disconnected, the alarm output will not turn OFF even after reconnecting the sensor. To disengage the alarm output, the temperature controller power must be reset.

#### O Dual PID control

The response rate of the PID control can be selected depending on the characteristics of the control target. Select high-speed response mode or low-speed response mode [ $Pi\ dF$ ,  $Pi\ d.5$ ] from PID method [ $Pi\ dE$ ] of parameter group 2.



#### 

Used to correct deviation from external devices such as temperature controllers.

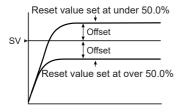
E.g.)If the actual temperature is 80°C but the display value is 78°C, set the input correction [l n-b] value to 2 and it will display 80°C as the display value.

#### Manual reset [¬ E 5 ₺ ]

When using proportional control (P control), the time of temperature rising time and falling time may differ depending on factors such as the heat capacity of the control device or the heater. A certain amount of deviation occurs even under stable conditions.

This deviation is referred to as offset, and can be configured/corrected using manual reset [ $_{\it E}$ 5 $_{\it E}$ ]. When PV and SV are equal, the reset value is 50.0%. If the PV is lower than the SV during stable control, set the value to over 50.0%, and if the PV is higher than the SV, set the value to under 50.0%

• Configuring manual reset [r E 5 ½] according to control results.



### ■ RS485 Communication

Applicable for models that support RS485 communication. Please refer to '■ Ordering Information'.

It is used to transmit PV or SV, and/or set the SV.

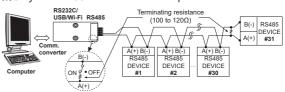
#### 

BCC
EIA RS485
31 units (address: 1 to 99)
2-wire half duplex
Asynchronous
Within 1.2km
2400, 4800, 9600bps
1-bit fixed
8-bit fixed
None
1-bit fixed

XIt is not allowed to set overlapping communication address at the same communication line. Use twisted pair wire for RS485 communication.

### Application of system organization

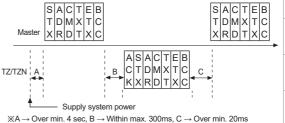
\*Only for RS485 communication output model.



XIt is recommended to use Autonics communication converter; SCM-WF48 (Wi-Fi to RS485·USB wireless communication converter, sold separately), SCM-US48I (USB to RS485 converter, sold separately), SCM-38I (RS232C to RS485 converter, sold separately). Please use twisted pair wire for RS485 communication.

#### Occurred Communication Control ordering

- 1. The communication control ordering of TZ/TZN Series is exclusive protocol.
- After 4 sec being supplied the power into master system, then able to start communicating.
- 3. Initial communication will be started by master system. When Command signal comes out from master system then TZ/TZN Series will respond.



SENSORS

CONTROLLERS

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SOFTWARE

J) Femperature Controllers

(K) SSRs

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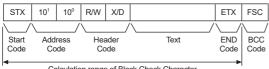
(V) HMIs

(W) Panel PC

(X) Field Network Devices

### © Communication command and block

Format of command and response



Calculation range of Block Check Character

① Start code

It indicates the first of Block STX  $\rightarrow$  [02H], in case of response, ACK will be added.

② Address code

This code is master system can discern TZ/TZN Series and able to set within range of 01 to 99. (BCD ASCII)

3 Header code

It indicates command as 2 alphabets as below.

RX (Read request) → R [52H], X [58H]

RD (Read response) → R [52H], D [44H]

WX (Write request) → W [57H], R [58H]

WD (Write response) → W [57H], D [44H]

- 4 Text: It indicates the detail contents of command/ response. (see command)
- ⑤ END code: It indicates the end of Block. ETX  $\rightarrow$  [03H]
- 6 BCC: It indicates XOR operating value from the first to ETX of the protocol as abbreviation of TZ/TZN.

#### **©** Communication command

#### • Read [RX] of measurement/setting value: address 01, command RX

- 1.Command (master)
- ① Command

STX	0	1	R	Х	Р	0	ETX	FSC
Start	Address			mand ad	P:Proce S:Settir	ss value	End	всс

② Application: address (01), header code (RX), process value (P)

STX	0	1	R	Х	Р	0	ETX	FSC
02	30	31	52	58	50	30	03	BCC

#### • Write [WX] of setting value: address 01, command WX

- 1.Command (master)
- ① Command

STX	0	1	W	Х	S	0	Symbol	10 <sup>3</sup>	10 <sup>2</sup>	10¹	10°	ETX	FSC
Start	Add	ress	Comi	mand ad	S:Se	tting	Space/-	10³	10²	10¹	10°	End	всс

2 Application: In case of writing address (01), heading coad (WX), setting value (S) +123

STX	0	1	W	Х	S	0	Symbol	10 <sup>3</sup>	10 <sup>2</sup>	10 <sup>1</sup>	10°	ETX	FSC
02	30	31	57	58	53	30	20	30	31	32	33	03	всс

#### Response

#### • Read of process/Setting value

1. In case of receiving normal process value: The data is transmitted adding ACK [60H]. (In case process value is +123.4)

A C K	S T X	0	1	R	D	Р	0	Symbol	10 <sup>3</sup>	10²	10¹	10°	Decimal point	E T X	F S C	NULL
A C K	S T X	0	1	R	D	Р	0	Space	1	2	3	4	1	E T X	ВСС	$N \cup L \cup L$
06	02	30	31	52	44	50	30	20	31	32	33	34	31	03	ВСС	00

2. In case process value is -100

	11 00	100	Pio	000	0 10	1140										
A C K	S T X	0	1	R	D	Р	0	_	0	1	0	0	0	E T X	ВСС	NULL
06	02	30	31	52	44	50	30	2D	30	31	30	30	30	03	B C C	00

XIt is responded with 1 byte sized NULL (00H) at the end of response frame (next BCC 16).

#### • Write of setting value

In case setting value is -100

				J										
A C K	S T X	0	1	w	D	S	0	Symbol	10 <sup>3</sup>	10 <sup>2</sup>	10¹	10°	E T X	F S C
A C K	S T X	0	1	W	D	S	0	_	0	1	0	0	E T X	B C C
06	02	30	31	57	44	53	30	2D	30	31	30	30	03	B C C

- Others: In case of no response of ACK
- ① When the address is not the same after receiving STX.
- ② When receiving buffer overflow is occurred.
- 3 When the baud rate or others communication setting value are not the same.
- When there are no ACK response
- ① Check the status of lines
- ② Check the communication condition (setting value)
- 3 When assuming the problem is due to noise, try to operate communication 3 times more until recovery.
- 4 When occurred communication failure frequently, please adjust the communicating speed.

### Error Display

Display	Description	Troubleshooting
oPEn	Blinks when input is disconnected.	Check input status.
нннн	Blinks when the measured input value is higher than the temperature range.	Adjust the value to within the temperature range.
LLLL	Blinks when the measured input value is lower than the temperature range.	

SENSORS

MOTION DEVICES

SOFTWARE

### Proper Usage

#### Troubleshooting

Symptoms	Troubleshooting
aPEn is displayed on the PV display during operation	Disconnect the power and check the input connection. If the input is connected, disconnect the input wiring from the temperature controller and short the + and - terminals. Power the temperature controller and check if it displays the room temperature. If it does not display the room temperature and continues to display a PEn, the controller is broken. Please contact our technical support. (Input type is thermocouple)
Load (heater, etc.) does not operate during operation	Check the state of the control output indicator on the front panel.  If the indicator is not working, check parameter settings. If the indicator is working, disconnect the wiring from the output terminal of the temperature controller and check the output (replay contact, SSR drive, current).
Erral (error) is displayed on the PV display during operation	Indicates damage to internal chip by strong noise (2kVAC). Please contact our technical support. Locate the source of the noise and devise countermeasures.

#### O Cautions during use

- Follow instructions in 'Cautions during Use'. Otherwise, It may cause unexpected accidents.
- Check the polarity of the terminals before wiring the temperature sensor.
   For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length.
   For thermocouple (CT) temperature sensor, use the designated compensation wire for extending wire.
- Keep away from high voltage lines or power lines to prevent inductive noise.
   In case installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line.

Do not use near the equipment which generates strong magnetic force or high frequency noise.

- Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.
- Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature controller.
- When changing the input sensor, turn off the power first before changing.
   After changing the input sensor, specify internal switch and modify the value of the corresponding parameter.
- Do not overlapping communication line and power line.
   Use twisted pair wire for communication line and connect ferrite bead at each end of line to reduce the effect of external noise.
- Make a required space around the unit for radiation of heat.
   For accurate temperature measurement, warm up the unit over 20 min after turning on the power.
- Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.
- Do not wire to terminals which are not used.
- This unit may be used in the following environments.
  - ①Indoors (in the environment condition rated in 'Specifications')
  - ②Altitude max. 2,000m
- ③Pollution degree 2
- ④Installation category II

(L)
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