

Through-beam Type Mapping Sensor

■ Features

- Double-scan method increases glass substrate detection stability
- Sensing distance: Glass generation+30%
- Models according to the orders (patent)
: sensing channels (4 to 62CH), optical axes pitch (min. 25mm)
- Communication output models: CC-LINK(ver. 2.0), EtherCAT
- Easy installation with installation guide mode
- Built-in mutual interference prevention, self-diagnosis function
- Built-in optical axis misalignment alarm, sensing 9-level setting, emitter damage alarm



SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

⚠ Please read "Safety Considerations" in the instruction manual before using.



(except EtherCAT model)

■ Applications

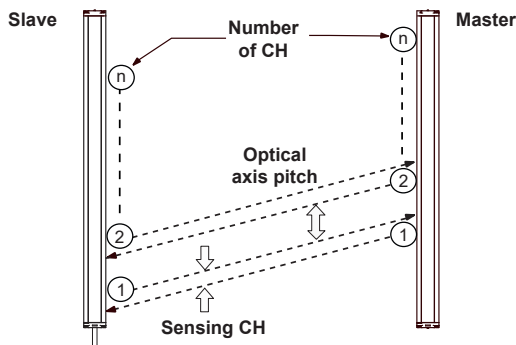
Applications: Detecting display glass on the cassette, etc.

■ Ordering Information

BWM	82	-	24	CL	D	-	-	/	
Item	Sensing CH*1	Optical axis pitch*1	Control output	Operation mode	External device connection mode	CH ordering orientation	Custom order option		
	Number	Number	CL	D	No mark	No mark	No mark	No option	
	4 to 62CH	25 to 200mm	CL	D	No mark	No mark	No mark	No option	
			EC		R	A		Mixed sensing pitch	
					T	Number		Option	
					L				
					D				
					L				
					D				
					CL				
					EC				
					Number				
					4 to 62CH				
					Number				
					25 to 200mm				
					BWM				
					Through-beam type Mapping sensor				

※: This information is intended for product management of custom order option. (no need to refer when selecting model)

■ Number of CH, Optical Axis Pitch, Sensing CH



(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) LiDAR

(D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

(G) Pressure Sensors

(H) Rotary Encoders

(I) Connectors/ Connector Cables/ Sensor Distribution Boxes/ Sockets

BWM Series

■ Specification

● General specifications

Model	BWM□-□CL□-□□/□		BWM□-□EC□-□□/□
Control output	CC-LINK communication output		EtherCAT communication output
Sensing type	Through-beam type		
Sensing distance	Glass ±30%		
Sensing target	Transparent or opaque glass plate		
Optical axes pitch ^{※1}	25 to 200mm		
Sensing CH ^{※1}	4 to 62CH		
CH ordering orientation ^{※1}	Forward (bottom=1CH) / Backward (top=1CH)		
Beam pattern	Double scan type		
Power supply	24VDC= (ripple P-P: max. 10%)		
Synchronization type	Synchronized by synchronous cable		
Protection circuit	Reverse polarity protection circuit		
Current consumption	Master: max. 200mA, slave: max. 150mA		
Operation mode ^{※1}	Light ON/Dark ON		
Response time	Max. 120ms		
Light source	Infrared LED (850nm modulated)		
Noise immunity	The square wave noise by the noise simulator (voltage: 500V, period: 10ms, pulse width: 1us)		
Dielectric strength	Between all power input terminals and F.G. terminal: 500VAC 50/60Hz for 1 min Between communication input terminals and F.G. terminal: 1000VAC 50/60Hz for 1 min Between power input terminals and communication input terminals: 1000VAC 50/60Hz for 1 min		
Insulation resistance	Over 20MΩ (at 500VDC megger)		
Vibration	1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours		
Shock	210m/s ² (approx. 21G) in each X, Y, Z direction for 3 times		
Environment	Allowable illum.	Max. 5,000lx of light bulb or semiconductor	
	Allowable temp.	15 to 35°C, storage: 15 to 35°C	
	Allowable humi.	35 to 85%RH, storage: 35 to 85%RH	
Material	Case: aluminum, sensing part and Indicator part: polymethyl methacrylate		
Connector	Connector type	4-pin, 6-pin connector (5.08mm pitch)	4-pin connector (5.08mm pitch)
	Terminal type	10-pin terminal	4-pin terminal
Cable	Ø5mm, 6-wire, 250mm, M17 connector		
Accessory	Bracket A: 4, bracket B: 4, bolt: 8		
Approval	CE, RoHS, CC-LINK		CE
Weight ^{※2}	Approx. 5.3kg (approx. 3.2kg) (based on BWM82-24CLD-T)		Approx 5.52kg (approx 3.42kg) (based on BWM28-50ECD-T)

※1: This product is order made.

In case that you want to make an order for the product under 8 channels, please contact us.

※2: The weight includes packaging. The weight in parenthesis is for unit only.

※Environment resistance is rated at no freezing or condensation.

● CC-LINK communication output

Model	BWM□-□CL□-□□/□	
Version	CC-LINK Ver 1.1	CC-LINK Ver 2.0
Type of station	Remote Device Station	
Extended cyclic	—	1 time (single)
Number of occupied stations	1 station 32-point module, 2 station 64-point module	
Transmission speed	156kbps/625kbps/2.5Mbps/ 5Mbps/10Mbps	
Max. number of connection ^{※2}	42-unit	
Number of I/O points	1 station: 32-point (I/O allocation), 2 station: 64-point (I/O allocation)	

※1: The number of connectable units = $16 \times A + 54 \times B + 88 \times C \leq 2304$

- A: remote I/O station, max. 64 units
- B: remote device station, max. 42 units
- C: local, intelligent station, max. 26 units

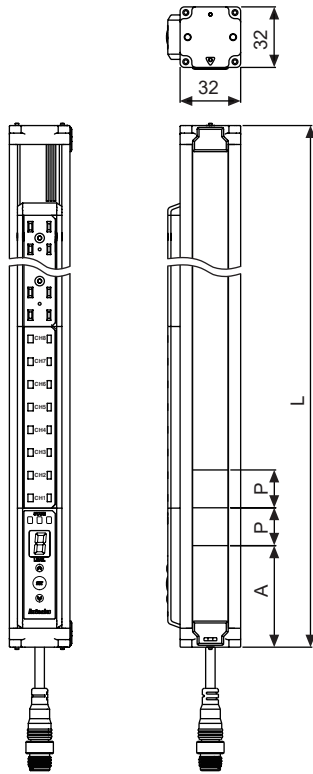
● EtherCAT communication output

Model	BWM□-□EC□-□□/□	
Comm. protocol	EtherCAT protocol	
Physical layer	100BASE-TX (IEEE 802.3u)	
Comm. medium	Over CATEGORY 5/E (must be shield cable)	
Connection method	Daisy chain	
Transmission speed	100Mbps	
Address range	0 to 65535 (16-bit)	
Address setting	Software (EtherCAT Master)	
Comm. range	Distance between nodes: max. 100M	

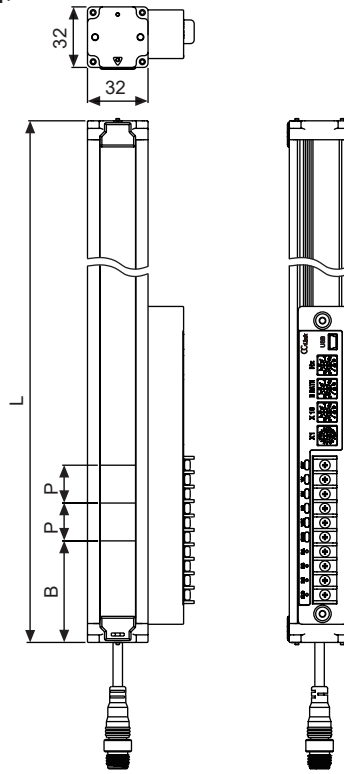
Through-beam Type Mapping Sensor

Dimensions

<Slave>

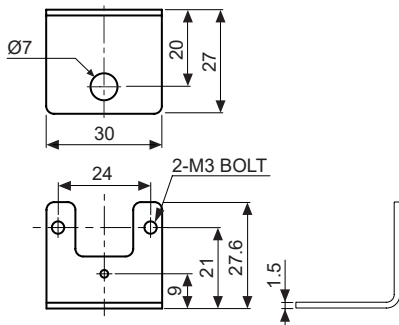


<Master>

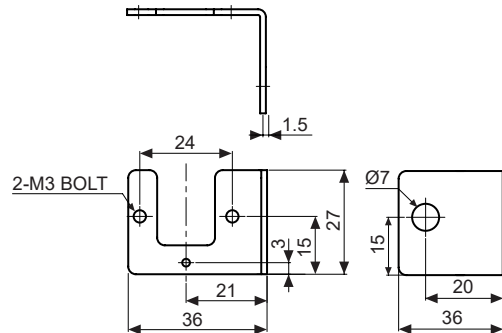


※Length of the product can be different by its ordered specification. Refer to the followings.
 length of the product (L) = 105+{optical axis pitch (P)×(sensing CH-1)}
 A: 45 to 65mm, B: 65 to 85mm

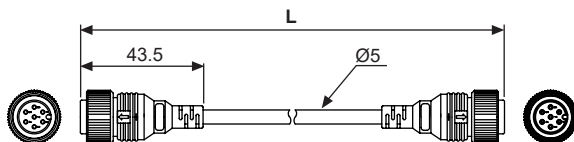
● Bracket A



● Bracket B



Connection Cable (sold separately)



Model	L
C5D617-7P	7m
C5D617-10P	10m
C5D617-15P	15m

SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) LIDAR

(D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

(G) Pressure Sensors

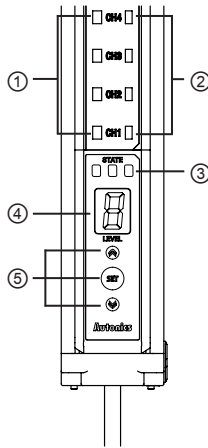
(H) Rotary Encoders

(I) Connectors/
Connector Cables/
Sensor Distribution
Boxes/ Sockets

BWM Series

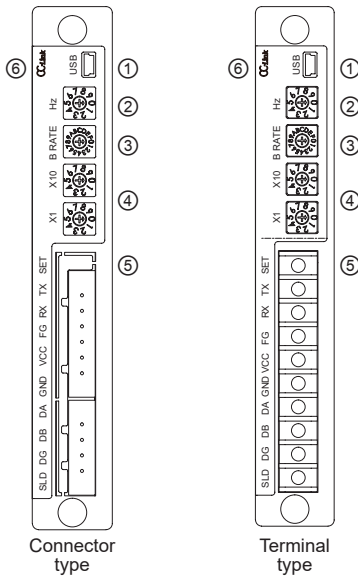
Unit Description

Slave

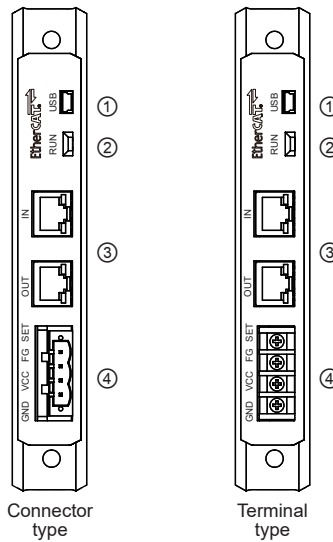


- ① Output indicator (red LED)
- ② Stability indicator (green LED)
- ③ Status indicator (green/yellow/red LED)
- ④ Status display
- ⑤ Mode setting key

CC-LINK Master



EtherCAT Master

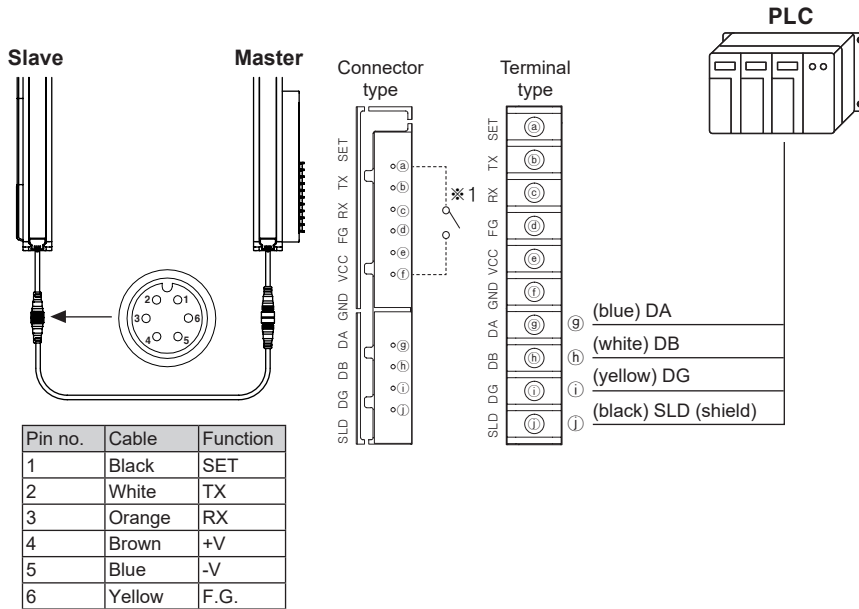


- ① USB port
 - : This port is only for firmware upgrade, run mode change, and A/S. Do not use this port for the another purpose, or the product can malfunction.
- ② Frequency setting switch (Hz)
 - : This switch is for setting mutual interference prevention function.
- ③ Comm. speed setting switch (B RATE)
 - : You can set CC-LINK communication speed.
- ④ Comm. address setting switch
 - : You can set CC-LINK address. ($\times 10: 10^1, \times 1: 10^0$)
- ⑤ Output part
 - connector type: 4-pin/6-pin connector, terminal type: 10-pin terminal
- ⑥ Comm. status indicator
 - : It displays the communication status through LED.

- ① USB port
 - : This port is only for firmware upgrade, run mode change, and A/S. Do not use this port for the another purpose, or the product can malfunction.
- ② Comm. status indicator
 - : It displays the communication status through LED.
- ③ EtherCAT comm. input/output connector
 - : It is with the communication status indicator which turns on or flashes according to the communication status.
- ④ Power and synchronous cable terminal

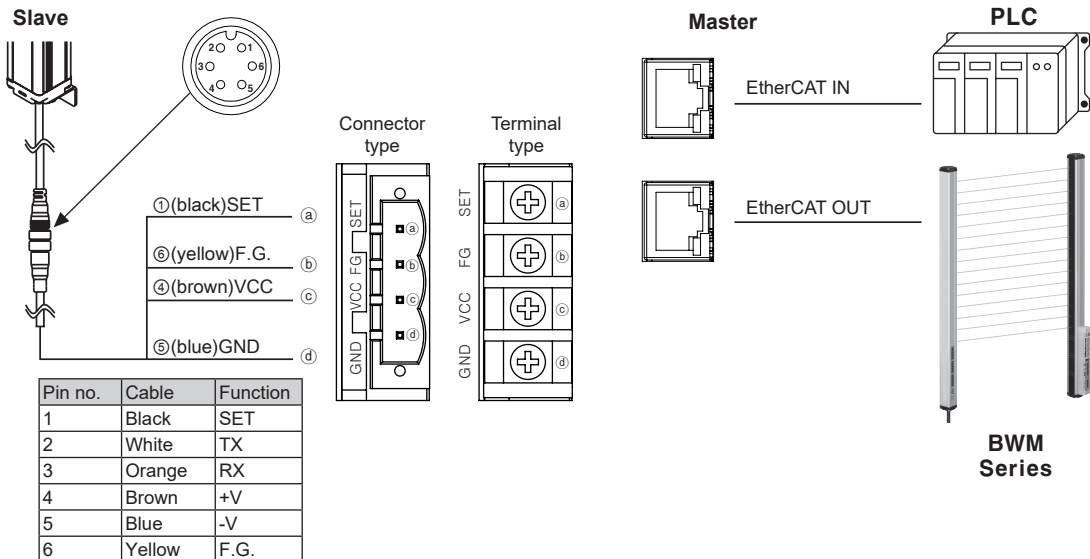
■ Connections

◎ CC-LINK communication output



※1: Instead of key, you can use SET, GND terminal for teaching from external signal.

◎ EtherCAT communication output



※1: Instead of key, you can use SET, GND terminal for teaching from external signal.

SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) LiDAR

(D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

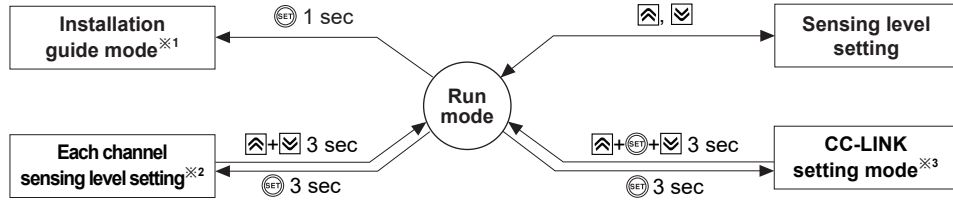
(G) Pressure Sensors

(H) Rotary Encoders

(I) Connectors/ Connector Cables/ Sensor Distribution Boxes/ Sockets

BWM Series

Mode Switching Method



※1: Entering to the installation guide mode and pressing **SET** key for 3 seconds starts teaching, and the product returns to the run mode after teaching completed.

※2: When the status display is *d*, select channel to change using **▲**, **▼** key and press **SET** key.

When number of channel is flashing, set sensing level using **▲**, **▼** key.

※3: Only for CC-LINK communication output model.

CC-LINK Baud Rate and Address Setting

• For CC-LINK setting, communication speed of PLC Master and BWM should be the same.

• Address is available from 1 to 64 and it should not be duplicated.

• When changing CC-LINK setting, turn OFF the power of this unit and re-supply it.

• Press **▲**+**SET**+**▼** key in the run mode and enter to the CC-LINK setting mode to set the version and the number of occupied station.

The number of occupied station: status display 5, 1 (station 1), 2 (station 2)

Version: status display 1, 1 (version 1.1), 2 (version 2.0)

Setting		Setting range
B RATE	Baud rate	0: 156kbps, 1: 625kbps, 2: 2.5Mbps 3: 5Mbps, 4: 10Mbps, 5 to F: not used
×10, ×1	Address of unit	0: master, 1 to 64: settable address, 65 to 99: not used E.g.) To set 12 as address, set ×10 to 1 and ×1 to 2.

EtherCAT I/O DATA Structure

※HIGH: ON, LOW: OFF for bit status.


1st Word	Description	2nd Word	Description
I/O0 [BIT0]	CH1 status	I/O0 [BIT0]	CH17 status
I/O1 [BIT1]	CH2 status	I/O1 [BIT1]	CH18 status
I/O2 [BIT2]	CH3 status	I/O2 [BIT2]	CH19 status
I/O3 [BIT3]	CH4 status	I/O3 [BIT3]	CH20 status
I/O4 [BIT4]	CH5 status	I/O4 [BIT4]	CH21 status
I/O5 [BIT5]	CH6 status	I/O5 [BIT5]	CH22 status
I/O6 [BIT6]	CH7 status	I/O6 [BIT6]	CH23 status
I/O7 [BIT7]	CH8 status	I/O7 [BIT7]	CH24 status
I/O8 [BIT8]	CH9 status	I/O8 [BIT8]	ERROR output BIT
I/O9 [BIT9]	CH10 status	I/O9 [BIT9]	ALARM output BIT
I/O10 [BIT10]	CH11 status	—	—
I/O11 [BIT11]	CH12 status		
I/O12 [BIT12]	CH13 status		
I/O13 [BIT13]	CH14 status		
I/O14 [BIT14]	CH15 status		
I/O15 [BIT15]	CH16 status		

※Since the above is based on the product of 24 CH, the number of I/O is changeable by product.

EtherCAT I/O data structure consists of the number of CH+ERROR output BIT+ALARM output Bit.

■ Function

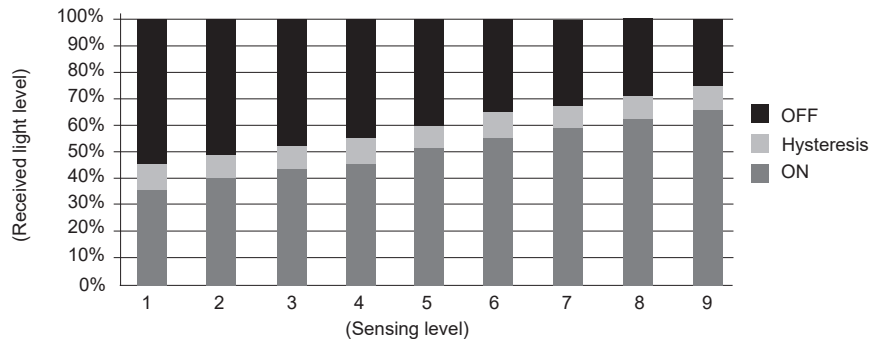
● Installation guide mode

This function displays whether the sensing target is in the stable position of the guide line when installing the product through the output indicator. Entering installation guide mode and pressing  key starts teaching. When teaching, this function detects channels with unstable received light level and adjust received light level of all channels to the same level.

● Sensing level setting

This function sets sensitivity by dividing received light into 9 levels for stable sensing. Use this function when some of the channels shows low sensing level due to the bent glass plate or diffused reflection. Factory default is level 5.

※ You can change sensing level of each channel separately in the each channel sensing level setting mode. When using the sensing level setting function after setting each channel sensing level using the each channel sensing level setting mode, sensing level settings of each channel are reset.



● Mutual interference prevention

When installing over 2 sensors closely, set the each frequency by the switch for frequency setting to prevent malfunction from mutual interference.

Mark	Freq.	Mark	Freq.
0	A	3	D
1	B	4 to 9	Not used
2	C		

● Optical axis misalignment alarm (low light intensity alarm)

Emitted light level can be reduced due to warped product or long-term usage. When nothing is detected during operation, this function checks received light level and outputs alarm at 'OFF level+approx. 3%' of received light level. Emitted light level is returned to the normal level with teaching.

● Emitter damage alarm

Outputs alarm when emitter is damaged due to the long-term usage of emitter elements or strong impact to the product.

● Self-diagnosis function

Mapping sensor is able to self-diagnose periodically in normal operation. If error occurs, status indicator displays in which part error occurs.

- Malfunction of synchronous line: If there is malfunction of synchronous line, it displays error and outputs signal.

※ For more information about operation indication display, refer to "■ Operation Indicator"

SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) LIDAR

(D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

(G) Pressure Sensors

(H) Rotary Encoders

(I) Connectors/ Connector Cables/ Sensor Distribution Boxes/ Sockets

BWM Series

■ Operation Indicator

◎ [Slave] CH indicator

(☀: light ON, ●: light OFF, ⦿: flashing at 0.5 sec interval)

Item	Output (red LED)	Stability (green LED)	Item	Output (red LED)	Stability (green LED)
Stable light ON	●	☀	Stable light OFF	☀	☀
Unstable light ON	●	●	Unstable light OFF	☀	●
Teaching error	⦿	⦿			

◎ [Slave] Status indicator

(☀: light ON, ●: light OFF, ⦿: flashing at 0.5 sec interval)

Item	CH indicator ^{※1}	Status display	Status			CC-LINK, EtherCAT output
			green	yellow	red	
Normal operation	—	Sensing level	☀	●	●	—
Teaching error	Flashing (error channel)	—	●	⦿	●	Outputting H at relevant CH, N+1
Malfunction of synchronous cable (communication error)	Flashing (all LED)	⦿ to ☀ or ⦿	⦿	⦿	⦿	Outputting H at N+1, Outputting H or L at N+2
Emitter damage	Flashing at 0.25 sec interval (LED of the CH)	n	⦿	●	⦿	Outputting H at 1 to N+1
Installation guide mode	Coinciding all CHs optical axis	n	☀	●	●	Outputting H at all CHs
	Optical axis coinciding CH		●	⦿	●	
	Optical axis not coinciding CH		●	⦿	●	
Teaching	Coinciding all CHs optical axis	t	☀	●	⦿	
	Optical axis coinciding CH		●	⦿	⦿	
	Optical axis not coinciding CH		●	⦿	⦿	
Optical axis misalignment alarm	—	—	⦿	☀	⦿	Outputting H at N+2
Individual optical axis controlling mode	Flashing (relevant CH)	⦿ to ☀	●	☀	☀	—
CC-LINK setting change ^{※2}	No. of occupied station	5	●	☀	☀	all CHs, Outputting N+1
	Version	⦿	●	☀	☀	

※1: Except normal operation, stability indicator (green) stands for the master and output indicator (red) stands for the slave.

※2: Only for CC-LINK communication output model.

※N stands for all channel.

◎ [Master] Communication status indicator (CC-LINK)



Item	Communication status
Connected status	Simultaneous ON (green, red LED)
Pre connection status	ON (green LED)
Error	ON (red LED)

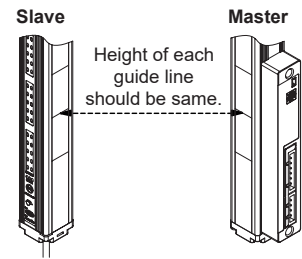
◎ [Master] Communication status indicator (EtherCAT)

Item	Communication status (green LED)	
RUN	Initial status	OFF
	Pre operation status	Flashing at 200ms interval
	Safe operation status	Repeating 200ms ON and 1000ms OFF
	Operation status	ON
L/A IN, L/A OUT	No connection	OFF
	Operation status	Flashing at 50ms interval
	Disconnection in operation	ON

Through-beam Type Mapping Sensor

Installation and Adjustment

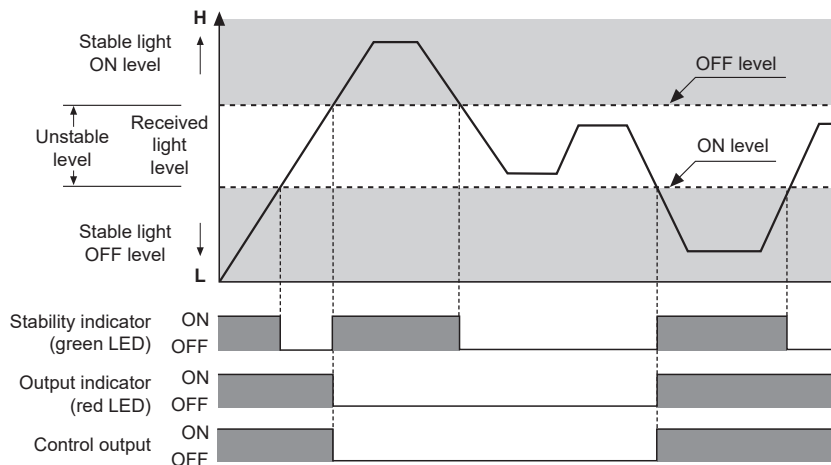
- ① Mount Master and Slave to face each other.
- ② Place a glass plate at the guide line and adjust sensor height.
- ③ Touch  key of Slave once without a glass plate and it enters installation guide mode. (Shorting SET (gray) and GND (blue) has same function.)
- ④ Adjust Master and Slave up/down/right/left, and check the place where output/stability indicators flash (displaying coincidence of optical axes of all CHs) and status indicator lights ON. Fix them at this place by tightening screws (tightening torque: 0.39 to 0.49 N·m).
- ⑤ Pressing  key for over 3 sec completes teaching and operates the device in RUN mode.



✗If optical axis are not coincident, yellow LED of the status indicator flashes at 0.5 sec interval, and output indicator (red, slave) and stable indicator (green, master) flash at 0.5 sec interval. Please re-adjust the position of Master and Slave and execute teaching again.

✗Avoid using the unit in the place where the sensor is exposed directly to the fluorescent light with high speed start or high frequency.

Operation Timing Diagram



✗The waveforms of 'Operation indicator' and 'Control output' are for Dark ON. The waveforms are reversed for Light ON.

Troubleshooting

Malfunction	Cause	Troubleshooting
Not operate	Power	Supply the rated power.
	Cable cut, disconnection	Check the wiring.
Not operate in sometimes	Sensor cover pollution by dirt	Remove dirt by soft brush or cloth and set sensitivity again.
	Connector connection failure	Check the connection area of connector.
Output is ON without a target	Initial sensitivity setting goes wrong	Remove the cause and set sensitivity again.
	There is a strong electric wave or noise generator.	Put away motor, electric generator, or high voltage line.

Proper Usage

1. Follow instructions in 'Proper Usage'. Otherwise, it may cause unexpected accidents.
2. 24VDC power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
3. Use the product, 1 sec after supplying power.
 - When using separate power supply for the sensor and load, supply power to sensor first.
4. When using switching mode power supply to supply the power, ground F.G. terminal and connect a condenser between 0V and F.G. terminal to remove noise.
5. When connecting a DC relay or other inductive load, remove surge by using diodes or varistors.
6. Wire as short as possible and keep away from high voltage lines or power lines, to prevent surge and inductive noise.
7. This unit may be used in the following environments.
 - ① Indoors (in the environment condition rated in 'Specifications')
 - ② Altitude max. 2,000m
 - ③ Pollution degree 2
 - ④ Installation category II

SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) LIDAR

(D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

(G) Pressure Sensors

(H) Rotary Encoders

(I) Connectors/ Connector Cables/ Sensor Distribution Boxes/ Sockets